

28. Quasiparticules etc...

8. $\eta_p \leftarrow$

29. Quelques résultats formels:

|| 1. Comportement asymptotique $\mathcal{G}(h, ik_n), \Sigma(h, ik_n)$

2. Causalité \leftarrow

30. Théorèmes généraux

✓ 1. Wick

✓ 2. Graphs connexes

✓ 3. Principe variationnel \leftarrow

Partie V : Gaz de Coulomb Jellium

31. Méthode générale: champs source, dérivée fonctionnelle

1. Exemple de physique statistique simple ←

2. H et notation

3. Equations du mouvement ✓

4. Dérivées fonctionnelles et structure du problème à N-corps ✓

$$A(k, \omega) = -2 \operatorname{Im} G^R = \frac{-2 \operatorname{Im} \Sigma^R(k, \omega)}{(\omega - \epsilon_k - \operatorname{Re} \Sigma^R(k, \omega))^2 + (\operatorname{Im} \Sigma^R)^2}$$

$$\begin{cases} \operatorname{Re} y = y' \\ \operatorname{Im} y = y'' \end{cases}$$

$$= \underbrace{Z_k}_{\substack{\text{Res} \\ \uparrow \\ \nu_k \rightarrow \nu_k^*}} \frac{1}{\pi} \frac{\Gamma(k, \omega)}{(\omega - \epsilon_k + i\eta)^2 + \Gamma(k, \omega)^2}$$

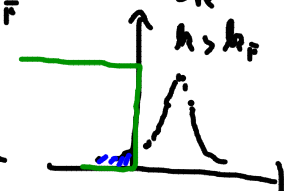
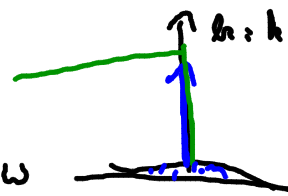
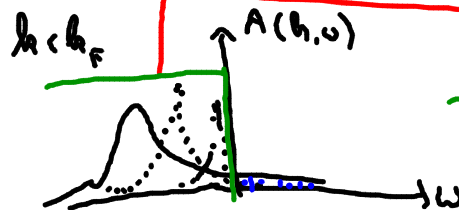
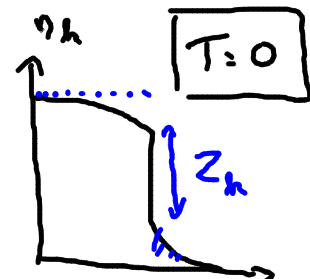
$$\begin{aligned} \Gamma &= -2 \operatorname{Im} \Sigma^R \\ \uparrow \\ Z_k &= \frac{1}{1 - \frac{\partial \Sigma^R}{\partial \omega} \Big|_{\omega = \epsilon_k + i\eta}} \\ \uparrow \end{aligned}$$

28.8 n_k

$$\int dt e^{i\omega t} \langle c_k^+ c_k(t) \rangle = \underline{f(\omega) A(k, \omega)}$$

$$Z \sim \omega^\nu$$

$$\int \frac{d\omega}{2\pi} f(\omega) A(k, \omega) = \langle c_k^+ c_k \rangle$$



29.1 Propriétés formelles

$$\underline{\mathcal{G}(ik_n)} = \int \frac{d\omega}{2\pi} \frac{A(k, \omega)}{ik_n - \omega} \xrightarrow{ik_n \text{ grad}} \left[\int \frac{d\omega'}{2\pi} A(k, \omega') \right] \frac{1}{ik_n}$$

$\rightarrow \left(\frac{1}{ik_n} \right) \leftarrow \text{Si vrai} \Rightarrow \text{anticom.} = \text{O.K.}$

$$\mathcal{G}(k, z) = - \langle T_c \overline{c_k(z)} c_k^+ \rangle$$

$$\mathcal{G}(k, 0^-) - \mathcal{G}(k, 0^+) = \langle c_k^+ c_k \rangle + \langle c_k c_k^+ \rangle = 1$$

$$T \sum_n \left(e^{-ik_n 0^-} - e^{-ik_n 0^+} \right) \left[\mathcal{G}(k, ik_n) - \frac{1}{ik_n} \right] + T \sum_n \left(e^{-ik_n 0^-} - e^{-ik_n 0^+} \right) \frac{1}{ik_n} = 1$$

29.2 Consolide

$$\text{Im} \Sigma^R(b, \omega) < 0$$

$$\text{Lehmann} \Rightarrow A(k, \omega) = -2 \text{Im} G^R(b, \omega) > 0$$

$$\text{Re} G^R(r, r'; \omega)^* = \text{Re} G^R(r', r; \omega)$$

$$\left(\langle n | \psi(r) | m \rangle \langle m | \psi^+(r') | n \rangle \right)^*$$

$$G^R = \frac{1}{\omega - \mathcal{E}_k - \Sigma^R}$$

31.1 Exemple méthode générale

$$Z = \text{Tr} \left[e^{-\beta(H - \mu N - hM)} \right]$$

$$\frac{\partial \ln Z}{\beta \partial h} = \frac{\text{Tr} (M e^{-\beta(H - \mu N - hM)})}{Z} = \langle M \rangle_h$$

$$\frac{\partial^2 \ln Z}{\beta^2 \partial h^2} = \langle MM \rangle \Big|_{h=0} - \langle M \rangle \langle M \rangle \Big|_{h=0}$$

$$\langle M(r_1) M(r_2) \rangle \Big|_{h=0} - \langle M(r_1) \rangle \langle M(r_2) \rangle \Big|_{h=0}$$

$$Z = \text{Tr} \left[e^{-\beta(H - \mu N - \int d^3r h(r) M(r))} \right]$$

$$\frac{\delta \ln Z}{\beta \delta h(r_1)} = \frac{1}{Z} \text{Tr} \left[e^{-\beta(H - \mu N - \int d^3r h(r) M(r))} \frac{\delta}{\delta h(r_1)} \int d^3r h(r) M(r) \right]$$

$$\frac{\delta h(r_1)}{\delta h(r_2)} = \delta(r_1 - r_2)$$

$$\frac{\partial y_1}{\partial y_2} = \delta_{12}$$

$$= \langle M(r_1) \rangle$$

$$\frac{\delta \ln Z[h]}{\beta \delta h(r_1)} = \langle M(r_1) \rangle$$

$$\frac{\delta^2 \ln Z[h]}{\beta^2 \delta h(r_1) \delta h(r_2)} = \langle M(r_1) M(r_2) \rangle - \langle M(r_1) \rangle \langle M(r_2) \rangle$$

Notre cas:

$$Z[\varphi] = \text{Tr} \left[e^{-\beta K} \mathcal{T}_2 e^{\int_{i_1} \int_{i_2} \psi_{\sigma}^{\dagger}(i) \varphi_{\sigma}(i, 2') \psi_{\sigma}(2')} \right]$$

$i' = (r_i, \tau_i)$

$$\int_{i_1} \equiv \int d^3 r_i \int d\tau_i$$

$$\frac{\delta \ln Z[\varphi]}{\delta \varphi(i, 2)} = \mathcal{G}(2, 1) \varphi = - \frac{\langle \mathcal{T}_2 U[\varphi] \psi(2) \psi^{\dagger}(1) \rangle}{\langle \mathcal{T}_2 U[\varphi] \rangle}$$

$\langle \mathcal{T}_2 U[\varphi] \psi^{\dagger}(1) \psi(2) \rangle / \langle \mathcal{T}_2 U[\varphi] \rangle$

$$H = h_0 \psi^\dagger \psi + V \psi^\dagger \psi^\dagger \psi \psi$$

$$\frac{\partial \psi}{\partial z} = \frac{\partial}{\partial z} [e^{kz} \psi e^{-kz}] = [k, \psi] = -h_0 \psi - V \psi^\dagger \psi \psi$$

$$\frac{\partial}{\partial z} \mathcal{H}(r, z; r', z') = h_0 \mathcal{H} + \varphi \mathcal{H} - V \langle \psi^\dagger \psi \psi \psi^\dagger \rangle$$

$$(\mathcal{H}_0^{-1} - \varphi) \mathcal{H} = 1 - V \langle \psi^\dagger \psi \psi \psi^\dagger \rangle_{\varphi=0} \quad \Sigma(i, j) \mathcal{H}(i, j)$$

$$(\mathcal{H}_0^{-1} - \varphi - \Sigma) \mathcal{H} = 1$$

$$\left. \frac{\delta \mathcal{H}_0}{\delta \varphi} \right|_{\varphi=0}$$

$$\frac{\delta (\mathcal{H}_0^{-1})}{\delta \varphi} = 0$$

$$\frac{\delta \mathcal{H}}{\delta \varphi} \mathcal{H}^{-1} + \mathcal{H} \frac{\delta \mathcal{H}^{-1}}{\delta \varphi} = 0$$

$$\frac{\delta \mathcal{H}}{\delta \varphi} = -\mathcal{H} \frac{\delta \mathcal{H}^{-1}}{\delta \varphi} \mathcal{H} = +\mathcal{H} \frac{\delta \varphi}{\delta \varphi} \mathcal{H} + \mathcal{H} \frac{\delta \Sigma}{\delta \varphi} \mathcal{H}$$

$$\frac{\delta \mathcal{H}}{\delta \varphi} = \mathcal{H} \frac{\delta \varphi}{\delta \varphi} \mathcal{H} + \mathcal{H} \left(\frac{\delta \Sigma}{\delta \varphi} \mathcal{H} + \mathcal{H} \frac{\delta \mathcal{H}}{\delta \varphi} \right)$$

$$\frac{\delta \Sigma}{\delta \varphi} = \frac{\delta \Sigma}{\delta \varphi} \frac{\delta \mathcal{H}}{\delta \varphi}$$

Vertex irreducible (canal particulation)

$$\left[1 - \mathcal{H} \frac{\delta \Sigma}{\delta \varphi} \mathcal{H} \right] \frac{\delta \mathcal{H}}{\delta \varphi} = \mathcal{H} \frac{\delta \varphi}{\delta \varphi} \mathcal{H}$$

$\delta(1-i) \delta(2-i)$ $\delta \mathcal{H}(i, j)$

$$\mathcal{H}(1, i) \frac{\delta \varphi(i, j)}{\delta \varphi(j, k)} \mathcal{H}(j, l)$$

$$\begin{aligned}
 & \mathcal{L}(1, \bar{1}) \quad \frac{\delta \Sigma(\bar{1}, \bar{2})}{\delta \varphi(3,4)} \quad \mathcal{L}(\bar{2}, 1') \\
 & = \mathcal{L}(1, \bar{2}) \left[\begin{array}{cc} \frac{\delta \Sigma(\bar{1}, \bar{2})}{\delta \varphi(3,4)} & \frac{\delta \mathcal{L}(\bar{3}, \bar{4})}{\delta \varphi(3,4)} \\ \frac{\delta \mathcal{L}(\bar{2}, \bar{4})}{\delta \varphi(3,4)} & \frac{\delta \mathcal{L}(\bar{3}, \bar{4})}{\delta \varphi(3,4)} \end{array} \right] \mathcal{L}(\bar{2}, 1') \\
 & \quad \quad \quad \underbrace{\hspace{10em}}
 \end{aligned}$$

31.2 H $K = H - \mu N$

$$H = \sum_{\sigma_1} \int d^3x, d^3x_2 \psi_{\sigma_1}^{\dagger}(x_1) \langle x_1 | H_0 | x_2 \rangle \psi_{\sigma_1}(x_2)$$

$$\langle x_1 | H_0 | x_2 \rangle = -\frac{\nabla_{x_2}^2}{2m} \delta(x_2 - x_1)$$

$$+ \frac{1}{2} \sum_{\sigma_1, \sigma_2} \int d^3x, d^3x_2 V(x_1 - x_2) \psi_{\sigma_1}^{\dagger}(x_1) \psi_{\sigma_2}^{\dagger}(x_2) \psi_{\sigma_1}(x_2) \psi_{\sigma_2}(x_1)$$

$$\frac{\partial \Psi_0(x, \tau)}{\partial \tau} = \sum_{\sigma_1} \int d^3x, d^3x_2 \langle x_1 | H_0 | x_2 \rangle [\psi_{\sigma_1}^{\dagger}(x_1) \psi_{\sigma_1}(x_2), \Psi_0(x)]$$

$$= - \int d^3x_2 \langle x | H_0 | x_2 \rangle \psi_{\sigma}(x_2)$$

$$[AB, C] = \{A, C\} B + A \{B, C\}$$

$$\boxed{\langle x_1 | \frac{p^2}{2m} | x_2 \rangle} = \int \frac{dp}{2\pi} \langle x_1 | p \rangle \underbrace{\frac{p^2}{2m}} \underbrace{\langle p | x_2 \rangle}$$

$$= \int \frac{d^3x}{2\pi} e^{ip(x_1 - x_2)} \frac{p^2}{2m} = -\frac{\nabla_{x_1}^2}{2m} \delta(x_1 - x_2)$$

$$\int d^3x \psi^\dagger(x) \left[-\frac{\nabla^2}{2m} \right] \psi(x) = \int d^3x (\nabla \psi^\dagger) \frac{1}{2m} (\nabla \psi)$$

$$\int d^3x_1 d^3x_2 \psi^\dagger(x_1) \left[-\frac{\nabla_{x_1}^2}{2m} \delta(x_2 - x_1) \right] \psi(x_2)$$