

32. Equations du mouvement pour \mathcal{D} en présence de sources

1. H et equs. pour $\Psi(1)$

✓ 2. Equs. du mvt pour \underline{Q}_q et déf. de Σ_q

✓ 3. Fonctions à 4 points de dérivées fonctionnelle

4. Σ à partir de dérivée fonctionnelle

33. Première étape: H.F. et R.P.A.

$$Z[h] = \text{Tr} \left[e^{-\beta K + \int d^2r \beta h(r) M(r)} \right]$$

$$\frac{\delta^2 \ln Z[h]}{\beta^2 \delta h(r_1) \delta h(r_2)} = \langle M(r_1) M(r_2) \rangle_h - \langle M(r_1) \rangle_h \langle M(r_2) \rangle_h$$

$$\mathcal{L}(1,2)_\varphi = - \frac{\langle T_\tau S[\varphi] \psi(1) \psi^\dagger(2) \rangle}{\langle T_\tau S[\varphi] \rangle}$$

$$\langle T_\tau S[\varphi] \rangle = T_\tau [e^{-\beta K} S[\varphi]] / T_\tau [e^{-\beta K}]$$

$$S[\varphi] = e^{-\psi^\dagger(\bar{1}) \varphi(\bar{1}, \bar{2}) \psi(\bar{2})}$$

$$l = (x_i, \tau_i, \sigma_i) \quad \bar{i} \rightarrow \int d^3x_i \int_0^\beta d\tau_i \sum_{\sigma_i}$$

$$32.1 \quad \text{H et } \frac{\partial \Psi_\sigma(x, z)}{\partial z} = [K, \Psi_\sigma(x, z)] \quad \Psi(z) = e^{Kz} \Psi_S e^{-Kz}$$

$$K = \sum_{\sigma_1} \int d^3x_1 \Psi_{\sigma_1}^\dagger(x_1) \left[-\frac{\nabla^2}{2m} \right] \Psi_{\sigma_1}(x_1) - \mu \sum_{\sigma_1} \int d^3x_1 \Psi_{\sigma_1}^\dagger(x_1) \Psi_{\sigma_1}(x_1)$$

$$+ \frac{1}{2} \sum_{\sigma_1, \sigma_2} \int d^3x_1 d^3x_2 \Psi_{\sigma_1}^\dagger(x_1) \Psi_{\sigma_1}^\dagger(x_2) V(x_1 - x_2) \Psi_{\sigma_2}(x_2) \Psi_{\sigma_1}(x_1)$$

$$[\Psi_{\sigma_1}^\dagger(x_1) \Psi_{\sigma_1}(x_1), \Psi_\sigma(x)] = -\delta_{\sigma_1, \sigma} \delta(x_1 - x) \Psi_{\sigma_1}(x_1)$$

$$\frac{\partial \Psi_\sigma(x, z)}{\partial z} = -\frac{\nabla^2}{2m} \Psi_\sigma(x, z) - \mu \Psi_\sigma(x, z) - \int d^3x_2 \sum_{\sigma_2} V(x - x_2) \Psi_{\sigma_2}^\dagger(x_2) \Psi_{\sigma_2}(x_2) \Psi_\sigma(x)$$

$$[\Psi^\dagger \Psi^\dagger \Psi \Psi, \Psi] = [\Psi^\dagger \Psi^\dagger, \Psi] \Psi \Psi$$

$$[\Psi_{\sigma_1}^\dagger(x_1) \Psi_{\sigma_2}^\dagger(x_2), \Psi_\sigma(x)] \Psi_{\sigma_2}(x_2) \Psi_{\sigma_1}(x_1)$$

$$= -\left\{ \Psi_{\sigma_1}^\dagger(x_1), \Psi_\sigma(x) \right\} \Psi_{\sigma_2}^\dagger(x_2) \Psi_{\sigma_2}(x_2) \Psi_{\sigma_1}(x_1)$$

$$+ \Psi_{\sigma_1}^\dagger \left\{ \Psi_{\sigma_2}^\dagger(x_2), \Psi_\sigma(x) \right\} \Psi_{\sigma_2}(x_2) \Psi_{\sigma_1}(x_1)$$

$$= -\delta_{\sigma_1, \sigma} \delta(x - x_1) \Psi_{\sigma_2}^\dagger(x_2) \Psi_{\sigma_2}(x_2) \Psi_{\sigma_1}(x_1)$$

$$+ \delta_{\sigma_2, \sigma} \delta(x - x_2) \Psi_{\sigma_1}^\dagger(x_1) \Psi_{\sigma_2}(x_2) \Psi_{\sigma_1}(x_1)$$

$$\frac{\partial \Psi(1)}{\partial \tau_1} = -\frac{\partial^2}{\partial m} \Psi(1) - \mu \Psi(1) - V(1-\bar{a}) \Psi(\bar{a}) \Psi(\bar{a}) \Psi(1)$$

$$V(1-2) = \frac{e^2}{4\pi\epsilon_0 |x_1 - x_2|} \delta(\tau_1 - \tau_2)$$

3D.3. Eqs. du mol pour \mathcal{G}

$$\frac{\partial}{\partial \tau_1} \mathcal{G}(1, 2)_\varphi = -\delta(1-2) + \left(-\frac{\nabla^2}{2m} - \mu \right) \mathcal{G}(1, 2)_\varphi - \varphi(1, \bar{2}) \mathcal{G}(\bar{2}, 2)$$

$$+ V(1-\bar{2}) \langle T_\tau \psi^\dagger(\bar{2}') \psi(\bar{2}) \psi(1) \psi^\dagger(2) \rangle_\varphi$$

$$\left[-\frac{\partial}{\partial \tau_1}, -\frac{\nabla^2}{2m} - \mu \right] \mathcal{G}(1, 2)_\varphi - \varphi(1, \bar{2}) \mathcal{G}(\bar{2}, 2)$$

$$= \delta(1-2) \left[-V(1-\bar{2}) \langle T_\tau \psi^\dagger(\bar{2}') \psi(\bar{2}) \psi(1) \psi^\dagger(2) \rangle_\varphi \right]$$

$$\left[\mathcal{G}_0^{-1}(1, \bar{2}) - \varphi(1, \bar{2}) \right] \mathcal{G}(\bar{2}, 2)_\varphi = \delta(1-2) + \left[\Sigma(1, \bar{2}) \right] \mathcal{G}(\bar{2}, 2)_\varphi$$

$$\mathcal{G}_0^{-1}(1, 2) = \left[-\frac{\partial}{\partial \tau_1}, -\frac{\nabla^2}{2m} - \mu \right] \delta(1-2)$$

$$\langle T_z S[\varphi] \psi(1) \psi^\dagger(2) \rangle$$

$$= \langle T_z e^{\int_0^t \psi^\dagger(\bar{1}) \varphi(\bar{1}, \bar{2}) \psi(\bar{2})} \psi(1) e^{-\int_0^{t_1} \psi^\dagger(\bar{1}) \varphi(\bar{1}, \bar{2}) \psi(\bar{2})} \psi^\dagger(2) \rangle$$

$$S[\varphi] = e^{-\int_0^t \psi^\dagger(\bar{1}) \varphi(\bar{1}, \bar{2}) \psi(\bar{2})}$$

$$\frac{\partial}{\partial \bar{z}_1} e^{-\int_0^t \psi^\dagger(\bar{1}) \varphi(\bar{1}, \bar{2}) \psi(\bar{2})}$$

$$= - \int_0^t d^3x \psi_\sigma^\dagger(x, \tau, \bar{1}) \varphi_{\sigma'}(x, \tau, \bar{2}) \psi(\bar{2})$$

$$\frac{\partial}{\partial y} e^{-\int_0^y dx f(x)} = e^{-\int_0^y dx f(x)} \left[\frac{\partial}{\partial y} \left[-\int_0^y dx f(x) \right] \right]$$

$$= e^{-\int_0^y dx f(x)} [-f(y)]$$

$$\frac{\partial}{\partial y} \left[\int_0^y dx x^2 \right] = \frac{\partial}{\partial y} \left. \frac{x^3}{3} \right|_0^y = \frac{\partial}{\partial y} \frac{y^3}{3} = y^2$$

39.4 Dérivée fonctionnelle pour fct. à 4 points :

$$\sum_{\varphi} \mathcal{Q}(1, \bar{2}) \mathcal{Q}(\bar{2}, 2) = -\mathcal{V}(1, \bar{2}) \langle T_{\tau} \psi(\bar{2}^+) \psi(\bar{2}) \psi(1) \psi^+(2) \rangle_{\varphi}$$

$$\mathcal{Q}(1, 2)_{\varphi} = - \frac{\langle T_{\tau} S[\varphi] \psi(1) \psi^+(2) \rangle}{\langle T_{\tau} S[\varphi] \rangle}$$

$$\frac{\delta}{\delta \varphi(3, \varphi)} e^{-\psi^+(1) \varphi(\bar{1}, \bar{2}) \psi(\bar{2})} = -\psi^+(3) \psi(4) S[\varphi]$$

$$\left\{ \frac{\delta \mathcal{Q}(1, 2)_{\varphi}}{\delta \varphi(\bar{2}^+, \bar{2})} = \langle T_{\tau} \psi^+(\bar{2}^+) \psi(\bar{2}) \psi(1) \psi^+(2) \rangle_{\varphi} \right.$$

$$= \frac{1}{\langle T_{\tau} S[\varphi] \rangle^2} \langle T_{\tau} S[\varphi] \psi(1) \psi^+(2) \rangle \langle T_{\tau} S[\varphi] \psi^+(\bar{2}^+) \psi(\bar{2}) \rangle$$

$$= \langle T_{\tau} \psi^+(\bar{2}^+) \psi(\bar{2}) \psi(1) \psi^+(2) \rangle + \mathcal{Q}(1, 2) \mathcal{Q}(\bar{2}, \bar{2}^+)$$

$$\Sigma(1, \bar{3})_q \mathcal{G}(\bar{3}, 2)_q = -V(1, \bar{3}) \left[\frac{\delta \mathcal{G}(1, \bar{2})}{\delta \varphi(\bar{3}^+, \bar{3})} - \mathcal{G}(1, \bar{2}) \mathcal{G}(\bar{3}, \bar{3}^+) \right]$$

$$\mathcal{G}_q \mathcal{G}_q^{-1} = 1 ; \quad \frac{\delta}{\delta \varphi} [\mathcal{G}_q \mathcal{G}_q^{-1}] = 0$$

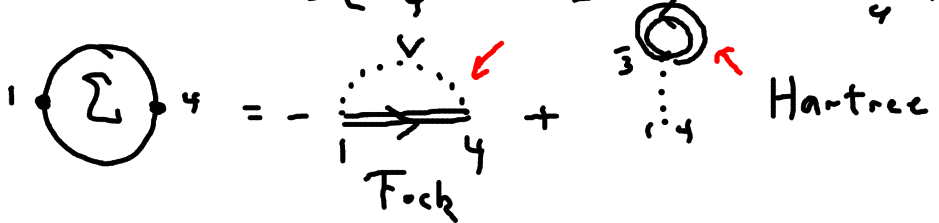
$$\frac{\delta \mathcal{G}_q \mathcal{G}_q^{-1}}{\delta \varphi} = -\mathcal{G}_q \frac{\delta \mathcal{G}_q^{-1}}{\delta \varphi} = -\mathcal{G}_q \frac{\delta}{\delta \varphi} [\mathcal{G}_q^{-1} - \varphi - \Sigma] = \mathcal{G}_q \frac{\delta \varphi}{\delta \varphi} + \mathcal{G}_q \frac{\delta \Sigma}{\delta \varphi}$$

$$\left(\Sigma \mathcal{G}(\bar{3}, \bar{3}) \right) \mathcal{G}^{-1}(\bar{2}, 4)$$

$$\Sigma(1, 4) = -V(1, \bar{3}) \left[\frac{\delta \mathcal{G}_q(1, \bar{2})}{\delta \varphi(\bar{3}^+, \bar{3})} \mathcal{G}_q^{-1}(\bar{2}, 4) - \mathcal{G}_q(\bar{3}, \bar{3}^+) \delta(4-1) \right]$$

$$= -V(1, \bar{3}) \left[\mathcal{G}_q(1, \bar{2}) \frac{\delta \varphi(\bar{2}, 4)}{\delta \varphi(\bar{3}^+, \bar{3})} - \mathcal{G}_q(\bar{3}, \bar{3}^+) \delta(4-1) \right]$$

$$= -V(1, 4) \left[\mathcal{G}_q(1, 4) \right] + V(1, \bar{3}) \mathcal{G}_q(\bar{3}, \bar{3}^+) \delta(4-1)$$



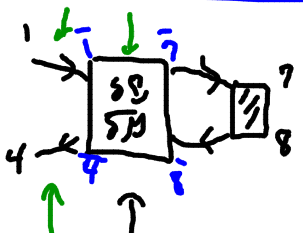
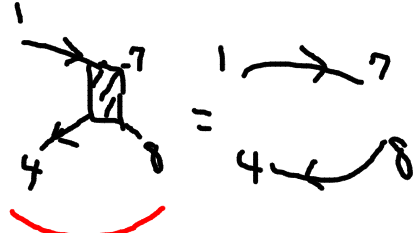
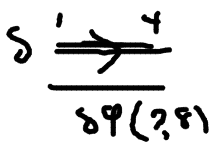
$$\mathcal{G}(1, 4) = \text{Fock diagram} \quad \mathcal{G}_1 \dots \mathcal{G}_4 = V(1, 4)$$

$$\frac{\delta \mathcal{L}}{\delta \varphi} = - \mathcal{L}' \frac{\delta \varphi}{\delta \varphi} = \mathcal{L}' \frac{\delta \varphi}{\delta \varphi} + \mathcal{L} \frac{\delta \Sigma}{\delta \varphi}$$

$$\frac{\delta \Sigma}{\delta \varphi} = \frac{\delta \Sigma}{\delta \mathcal{L}} \frac{\delta \mathcal{L}}{\delta \varphi}$$

$$\Sigma_q(1,4) = -V(1-4) \mathcal{L}_q(1,4) + V(1-\bar{3}) \mathcal{L}_q(\bar{3}, \bar{3}^+) \delta(1-4)$$

$$\frac{\delta \Sigma_q(1,4)}{\delta \mathcal{L}_q(5,6)} = -V(1-4) \delta(5-1) \delta(6-4) + V(1-\bar{3}) \delta(1-4) \delta(\bar{3}-5) \delta(\bar{3}-6)$$



$$\frac{\mathcal{L}(1,\bar{3}) \delta \mathcal{L}(\bar{3},\bar{3}^+) \mathcal{L}(\bar{3},4)}{\delta \mathcal{L}(7,8)}$$

Vertex irréductible

