

CH. 1 : ELEMENTS OF TOPOLOGICAL BAND THEORY

[Ref : P. Brune ,
arXiv : 050627 (2005)]

M. Berry (1983):

A quantum system adiabatically transported around a closed circuit acquires, besides the familiar dynamical phase, a phase that depends only on the geometry of the circuit.

"Berry phase" : central concept in quantum mechanics,

with applications ranging from chemistry to condensed matter physics to quantum information.

① Parallel transport in geometry

Consider a surface S^1 , and a vector tangent to it.

We want to transport the vector on the surface:

(i) vector is always tangent to S^1

(ii) do not rotate vector around the axis normal to the surface.

(i) + (ii) : "parallel transport".

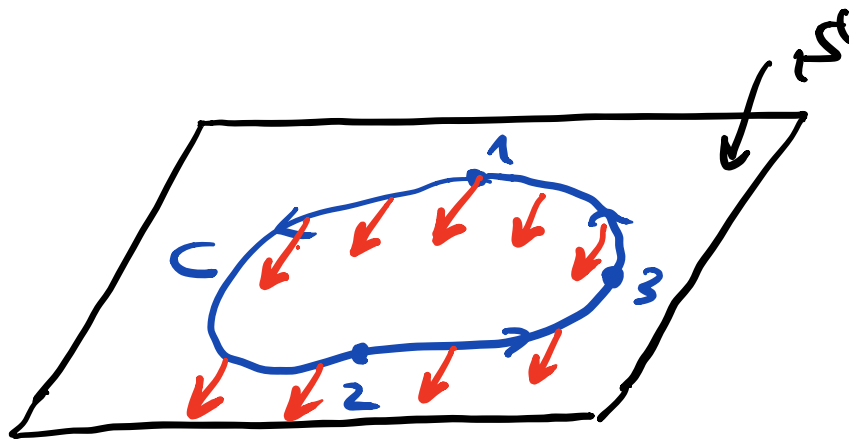
Consider a closed path C :

$$1 \rightarrow 2 \rightarrow 3 \rightarrow 1$$

Two scenarios :

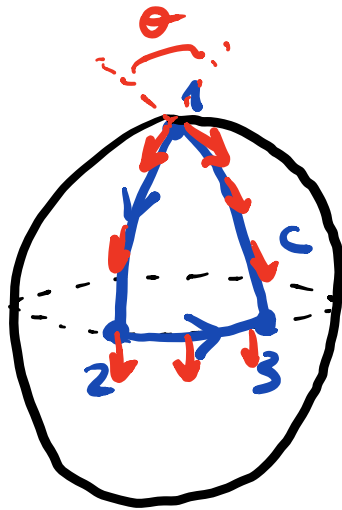
(1) $\mathbb{R}^2$ is flat

$\Rightarrow$ the vector that is transported always points in the same direction.



(2) ψ is curved

$\Rightarrow$ the vector changes direction as it moves along C .



The vector's initial direction differs from the final one by an angle $\theta(C)$

"holonomy"

geometric counterpart of the Berry phase.

A more quantitative discussions

Transported vector: $\hat{e}_1$

$$\hat{e}_1 \cdot \hat{e}_1 = 1$$

Loop: $C \equiv \{ \vec{r}(t) \mid t: 0 \rightarrow T \}$

time

$$\vec{r}(0) = \vec{r}(T)$$

$\hat{n}$ = unit vector normal to S .

$$= \hat{n}(\vec{r})$$

$$\hat{e}_1 \cdot \hat{n} = 0 \quad \text{for all } \vec{r} \in S$$

Another tangent vector:

$$\hat{e}_2 = \hat{n} \times \hat{e}_1$$

$$(\hat{e}_2 \cdot \hat{n} = 0)$$

$(\hat{e}_1, \hat{e}_2, \hat{n}) = \text{orthonormal}$
reference system.

Equation of motion for
 $\hat{e}_1$ as it is transported
along C ?

Impose that $\hat{e}_1 \cdot \hat{e}_1 = 1$
for all $\vec{r} \in S$

$$\Rightarrow \underbrace{\frac{d}{dt} (\hat{e}_1 \cdot \hat{e}_1)}_{\uparrow} = 0$$

$$2 \hat{e}_1 \cdot \frac{d\hat{e}_1}{dt}$$

$$\Rightarrow \frac{d\hat{e}_1}{dt} \perp \hat{e}_1$$

$$(\dot{\hat{e}}_1 \perp \hat{e}_1)$$

$$\boxed{\dot{\hat{e}}_1 = \vec{\omega} \times \hat{e}_1} \leftarrow$$

angular frequency
of rotation (TBD)

Similarly,

$$\boxed{\dot{\hat{e}}_2 = \vec{\omega} \times \hat{e}_2} \leftarrow$$

Need:

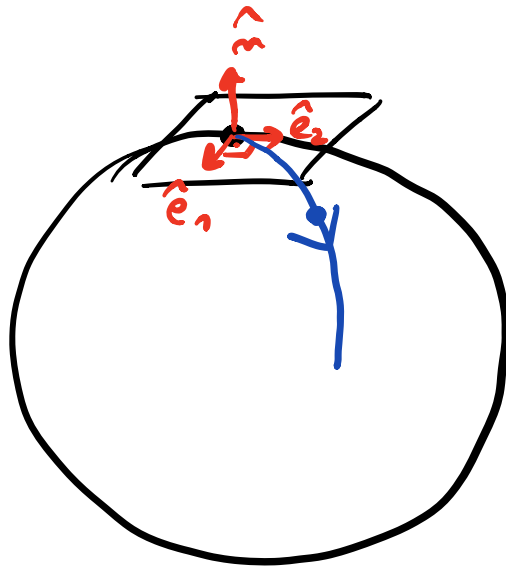
$$(i) \hat{e}_i \cdot \hat{n} = 0 \quad (i = 1, 2)$$

$$(ii) \underline{\vec{\omega} \cdot \hat{n}} = 0 \quad \checkmark$$

(parallel transport)

$\Rightarrow$
 $\uparrow$
 they're
 satisfied
 if

$$\vec{\omega} = \hat{n} \times \dot{\hat{n}}$$



In sum,

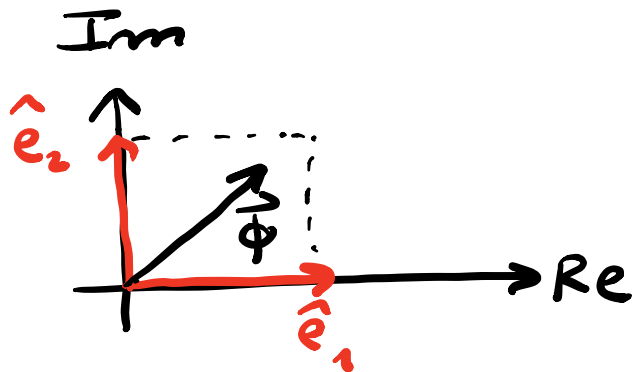
$$\begin{aligned}
 \left[\begin{aligned} \dot{\hat{e}}_i &= (\hat{n} \times \dot{\hat{n}}) \times \hat{e}_i \\ &= -(\hat{e}_i \cdot \dot{\hat{n}}) \hat{n} \end{aligned} \right] \quad (1)
 \end{aligned}$$

$\uparrow$
 standard
 vector relation

"law of parallel transport"

Let's reformulate this
(in anticipation to its
generalisation to quantum
case) :

$$\vec{\phi} \equiv \frac{1}{\sqrt{2}} (\hat{e}_1 + i \hat{e}_2)$$



$$\vec{\phi}^* \cdot \vec{\phi} = 1$$

The law of parallel transport
(1)

implies

$$\boxed{\vec{\phi}^* \cdot \dot{\vec{\phi}} = 0} \quad (2)$$

To express the rotation of $\hat{e}_1$ and $\hat{e}_2$ as they move along C , we choose a fixed local orthonormal frame on S :

$$\left(\underbrace{\hat{t}_1, \hat{t}_2}_{\text{tangent to } S'} , \underbrace{\hat{n}}_{\perp \text{ to } S'} \right)$$

$$\hat{t}_i = \hat{t}_i(\vec{r})$$

Impose:

$$\left\{ \begin{array}{l} \hat{t}_1 \text{ is continuously differentiable} \\ \text{w.r.t. } \vec{r} \\ \hat{t}_1 \text{ is single-valued.} \end{array} \right.$$

↑
notice that
 $(\hat{e}_1, \hat{e}_2, \hat{n})$ is not
single-valued at
point 1 if

$$\theta \neq 0.$$

$$\hat{t}_2 = \hat{n} \times \hat{t}_1$$

example:



$$(\hat{t}_1, \hat{t}_2, \hat{n}) = (\underbrace{\hat{\theta}, \hat{\phi}, \hat{r}}_{\substack{\text{unit vectors} \\ \text{in spherical} \\ \text{coordinates}}})$$

Now define

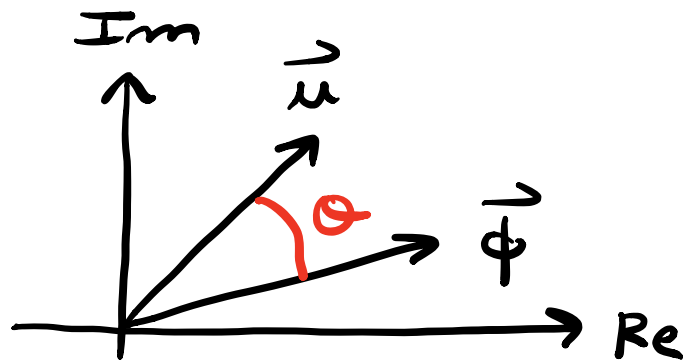
$$\vec{u} \equiv \frac{1}{\sqrt{2}} (\hat{t}_1 + i \hat{t}_2)$$

$$\vec{u}^* \cdot \vec{u} = 1$$

Relation between $(\hat{e}_1, \hat{e}_2, \hat{n})$
and $(\hat{t}_1, \hat{t}_2, \hat{n})$:

$$\vec{\phi}(t) = e^{-i\theta(t)} \vec{u}(t)$$

(3)



θ : angle by which we need to rotate $(\hat{t}_1, \hat{t}_2)$ to make them coincide with $(\hat{e}_1, \hat{e}_2)$.

Equation for θ ?

From (2) :

$$\begin{aligned} 0 &= \vec{\phi}^* \cdot \dot{\vec{\phi}} \\ &= -i\dot{\theta} + \vec{\mu}^* \cdot \dot{\vec{\mu}} \end{aligned}$$

$\uparrow$
(3)

$$\Rightarrow \boxed{\dot{\theta} = -i \vec{u}^* \cdot \dot{\vec{u}}}$$

θ must be real

$\Rightarrow \vec{u}^* \cdot \dot{\vec{u}}$ is pure imaginary.

$$\dot{\theta} = \text{Im} (\vec{u}^* \cdot \dot{\vec{u}})$$

$$\Rightarrow \boxed{\theta = \text{Im} \int_0^T \vec{u}^* \cdot \dot{\vec{u}} dt}$$

$$\theta \equiv 0 \text{ at } t = 0.$$

Alternatively,

$$\theta = \text{Im} \oint_c \vec{u}^* \cdot d\vec{u}$$

$$\dot{\vec{u}} dt = \frac{d\vec{u}}{dt} dt = d\vec{u}$$